



Magnet Gripperfor Collaborative Robots

YASKAWA Electric Corporation

collaborative robots MOTOMAN-HC10/HC10DT compliant





Magnet Gripper

for Collaborative Robots

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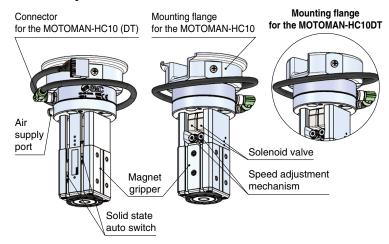
MOTOMAN-HC10/HC10DT compliant

- Attracts and holds heavy objects with a magnet
- Supports workpieces with holes and uneven surfaces
- Compact with high holding force
 - Holding force: Max. 200 N (Ø25, Workpiece thickness 6 mm)
- Continues to hold workpieces even when the air is shut off
- Operate by simply connecting 1 air supply tube and an electrical wiring connector.
- Integrated solenoid valve, auto switch, and piston speed adjustment mechanism



Learn more about the MHM series here.

Component Parts



How to Order



MHM-25D-X7400A-HC10-P

Compatible robot

HC10	MOTOMAN-HC10
HC10DT	MOTOMAN-HC10DT

 The supplied flange differs depending on the product number

	Auto switch output type			
Symbol	Auto switch model	Output type		
N	D-M9N	NPN		

D-M9P

Specifications

Fluid		Air	
Action		Double acting	
Operating pressure [MPa]		0.2 to 0.6	
Proof pressure [MPa] Ambient and fluid temperatures [°C]		0.9	
		-10 to 50 (No freezing)	
Holding	Workpiece thickness: 2 mm	160	
force [N]	Workpiece thickness: 6 mm	200	
Residual holding force [N]		0.3 or less	
Lubrication		Non-lube	
Weight [g]		800	
Auto switch model		D-M9N, D-M9P	
Connector type		Molex 51227-0800	

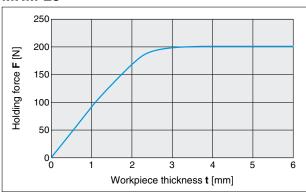
■ Included parts: Robot mounting flange, Conversion cable,
Mounting bolt, Piping tube (ø4 x 2 m), Cable fixture

Characteristics

Holding force

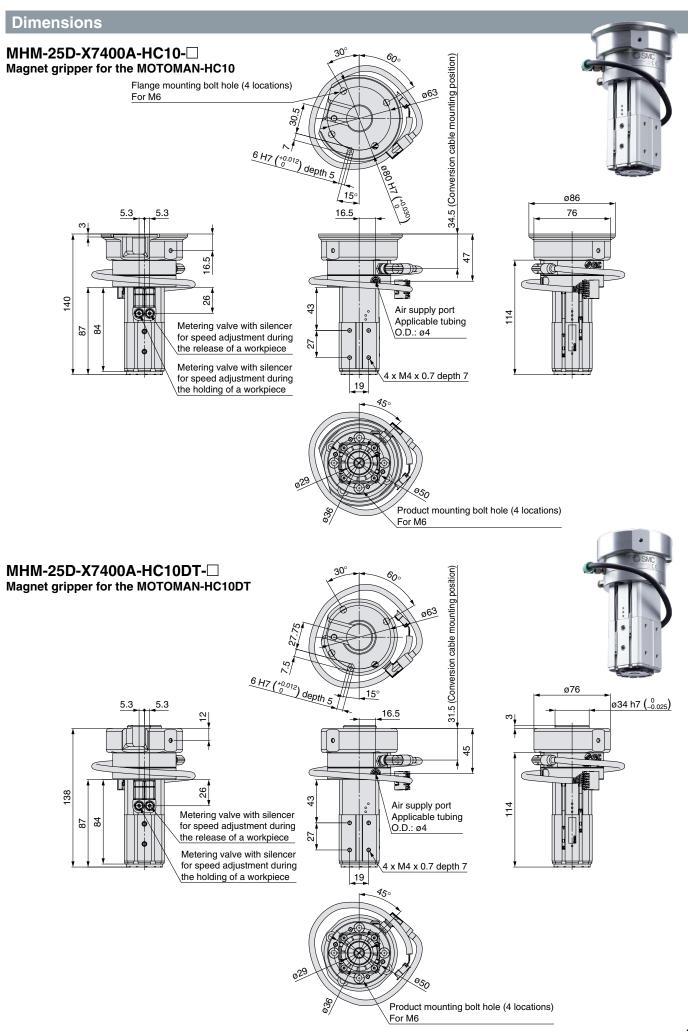
The holding force graph shows the theoretical value for low-carbon steel plates. Holding forces vary depending on the material and shape of the workpiece. Please perform a holding test while referring to the value selected based on the graph.

MHM-25



PNP

^{*} It can be used with robot specifications with air piping.





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Safety Instructions Be sure to read the "Handling Precautions for SMC Products" (M-E03-3) and "Operation Manual" before use.

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