



Magnet Gripperfor Collaborative Robots

Mitsubishi Electric Corporation collaborative robot

MELFA ASSISTA compliant





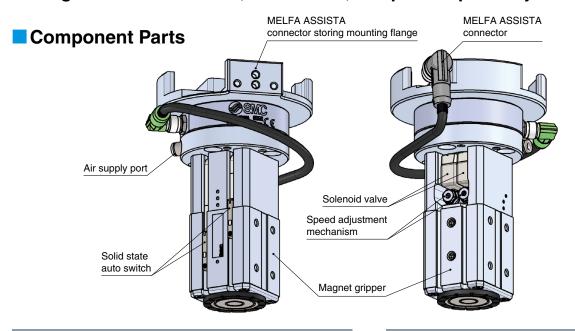


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- Attracts and holds heavy objects with a magnet
- Supports workpieces with holes and uneven surfaces
- Compact with high holding force
 - Holding force: Max. 200 N (Ø25, Workpiece thickness 6 mm)
- Continues to hold workpieces even when the air is shut off
- Operate by simply connecting 1 air supply tube and an electrical wiring M12 connector.
- Integrated solenoid valve, auto switch, and piston speed adjustment mechanism





Learn more about the MHM series here.

How to Order



MHM-25D-X7400A-ASSISTA-P

Auto switch output type

Symbol	Auto switch model	Output type
Nil	D-M9N	NPN
Р	D-M9P	PNP

Specifications

Fluid		Air	
Action		Double acting	
Operating pressure [MPa]		0.2 to 0.6	
Proof pressure [MPa]		0.9	
Ambient and fluid temperatures [°C]		-10 to 50 (No freezing)	
Holding force [N]	Workpiece thickness: 2 mm	160	
	Workpiece thickness: 6 mm	200	
Residual holding force [N]		0.3 or less	
Lubrication		Non-lube	
Weight [g]		780	
Standards		ISO 9409-1-31.5-4-M5	
Auto switch model		D-M9N, D-M9P	
Connector type		M12 8-pin connector (Plug)	

■ Included parts: Connector storing flange, Mounting bolt, Positioning pin, Coil tube for piping (ø4), Piping fittings (2 types)



Characteristics

Holding force

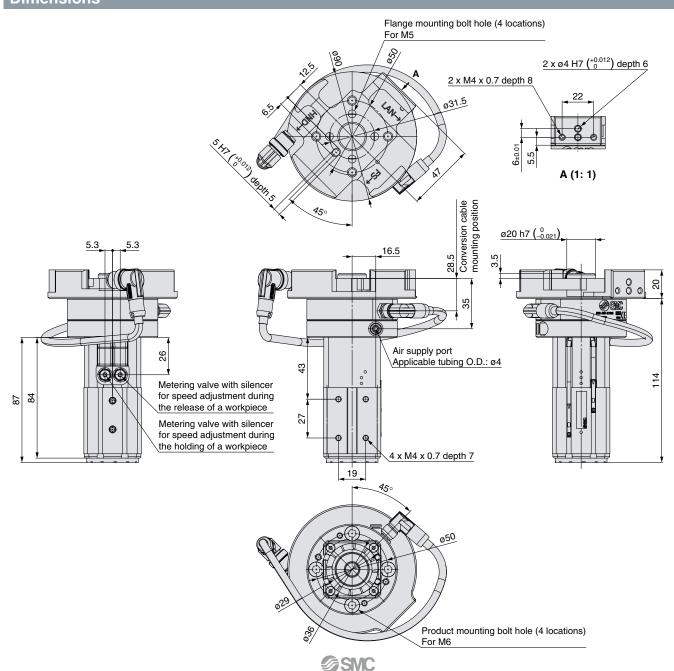
The holding force graph shows the theoretical value for low-carbon steel plates. Holding forces vary depending on the material and shape of the workpiece. Please perform a holding test while referring to the value selected based on the graph.

MHM-25





Dimensions





Magnet Gripper

for Collaborative Robots



Safety Instructions Be sure to read the "Handling Precautions for SMC Products" (M-E03-3) and "Operation Manual" before use.

SMC Corporation

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