# Peripherals overview





# Peripherals overview

Acces	sories		
	Туре	Description	→ Page/Internet
[1]	Toothed belt axis ELGA-TB-KF	Electric drive	12
[2]	Centring pin/sleeve ZBS, ZBH	<ul> <li>For centring loads and attachments on the slide</li> <li>Included in the scope of delivery: <ul> <li>With size 70: 2x ZBS-5</li> <li>With size 80, 120, 150: 2x ZBH-9</li> </ul> </li> </ul>	108
[3]	Switch lug SF-EGC	For sensing the slide position	105
[4]	Sensor bracket HWS-EGC	For mounting the inductive proximity switches (round design) on the axis	106
[5]	Proximity switch, M8 SIEN-M8	Inductive proximity switch, round design	110
[6]	Clamping element EADT	Tool for retensioning the cover strip	108
[7]	Axial kit EAMM	For axial motor mounting (comprising: coupling, coupling housing and motor flange)	94
[8]	Motor EMME, EMMS	Motors specially matched to the axis, with or without gear unit, with or without brake	94
[9]	Drive shaft EAMB	<ul> <li>Can, if required, be used as an alternative interface</li> <li>No drive shaft is required for the axis/motor combinations → page 94</li> </ul>	99
[10]	Slot cover ABP	For protection against contamination	108
[11]	Proximity switch, T-slot SIES-8M	<ul><li>Inductive proximity switch, for T-slot</li><li>The order code SA, SB includes 1 switch lug in the scope of delivery</li></ul>	109
[12]	Connecting cable NEBU, SIM	Via proximity switch	110
[13]	Clip SMBK	For mounting the proximity switch cable in the slot	108
[14]	Slot nut NST	For mounting attachments	108
[15]	Adapter kit DHAM	For mounting the support profile on the axis	109
[16]	Support profile HMIA	For mounting and guiding an energy chain	109
[17]	Profile mounting MUE	For mounting the axis on the side of the profile	101
[18	Adjusting kit EADC-E16	For mounting the axis on a vertical surface. Once mounted, the axis can be aligned horizontally	104
[19]	Central support EAHF-L5	For mounting the axis on the profile from underneath	102
[20]	Adjusting kit EADC-E15	Height-adjustable. Can be used to easily compensate for any unevenness in the bearing surface	103
[21]	Cover kit EASC-L5	For covering the sides of the drive cover	108
[22]	Foot mounting HPE	<ul> <li>For mounting the axis on the end cap</li> <li>With higher forces and torques, the axis should be mounted using the profile</li> </ul>	100

# Type codes

001	Series	008	Protection against particles	
ELGA	Gantry axis		Standard	
1		P11	Cover strip with magnetic deflection	
002	Drive system			
ТВ	Toothed belt	009	Additional characteristics	
1			None	
003	Guide	F1	Food-safe according to supplementary information on materials	
KF	Recirculating ball bearing guide	010	Displacement encoder	_
004	Size		None	
70	70	M1	With displacement encoder, incremental, resolution 2.5 µm	
80	80	M2	With displacement encoder, incremental, resolution 10 µm	
120	120			
150	150	011	Displacement encoder attachment position	
1			None	
005	Stroke range [mm]	F	Front	
	50 8500	В	Rear	
006	Stroke reserve	012	Material of toothed belt	
Н	0 999 mm	CR	Chloroprene rubber	
		PU1	Uncoated PU, FDA-compliant	
007	Additional slide	PU2	Coated PU	
	None			
ZL	1 slide left			
ZR	1 slide right			



#### General technical data

Size	70	80	120	150			
Design	Electromechanical axis w	Electromechanical axis with toothed belt					
Guide	Recirculating ball bearing	guide					
Mounting position	Any						
Working stroke	[mm]	50 5000	50 8500	50 8500	50 7000		
Max. feed force F <sub>x</sub>	[N]	350	800	1300	2000		
Max. no-load torque <sup>1)</sup>	[Nm]	0.6	1	2.8	4		
Max. no-load resistance to shifting <sup>1)</sup>	[N]	41.9	50.3	76.2	108.3		
Max. driving torque	[Nm]	5.02	15.92	34.1	73.85		
Max. speed	[m/s]	5	· ·		· · · · ·		
Max. acceleration	[m/s <sup>2</sup> ]	50					
Repetition accuracy	[mm]	±0.08	±0.08				

1) At 0.2 m/s

#### Operating and environmental conditions

Ambient temperature <sup>1)</sup>	[°C]	-10 +60
Degree of protection		IP40
Duty cycle	[%]	100

1) Note operating range of proximity switches

Weight [kg]					
Size	70	80	120	150	
Basic weight with 0 mm stroke <sup>1)</sup>	2.97	4.70	15.68	32.83	
Additional weight per 1000 mm stroke	3.94	5.13	10.64	17.22	
Moving mass					
ELGA	0.90	1.90	4.19	7.24	
ELGAZL/ZR	0.74	1.53	3.24	5.84	

1) Incl. slide

Toothed belt					
Size		70	80	120	150
Pitch	[mm]	3	5	5	8
Elongation <sup>1)</sup>	·				
ELGA	[%]	0.213	0.168	0.21	0.258
ELGAPU2	[%]	0.105	0.1	0.122	0.083
Effective diameter	[mm]	28.65	39.79	52.52	73.85
Feed constant	[mm/rev]	90	125	165	232

1) At max. feed force

### Data sheet

### Mass moments of inertia

Mass moments of inertia						
Size		70	80	120	150	
Jo	[kg mm <sup>2</sup> ]	243	982	4099	15426	
J <sub>H</sub> per metre stroke	[kg mm <sup>2</sup> /m]	19	93	215	586	
J <sub>L</sub> per kg payload	[kg mm <sup>2</sup> /kg]	205	396	690	1363	
J <sub>w</sub> for additional slide	[kg mm <sup>2</sup> ]	186	761	2891	9869	

The mass moment of inertia  $J_A$  of the  $J_A = J_0 + K x J_W + J_H x$  working stroke [m] +  $J_L x m_{payload}$  [kg] entire axis is calculated as follows:

K = Number of additional slides

## Materials



Axis					
Size		70	80	120	150
[1]	Drive cover	Anodised wrought aluminium alloy			
[2]	Cover strip	Stainless steel strip, non-corroding			
[3]	Toothed belt				
	ELGA	Polychloroprene with glass cord and nylon coating			
	ELGAPU2	Polyurethane with steel cord	and nylon cover		
[4]	Guide rail	Stainless steel		Tempered steel	
[5]	Slide	Anodised wrought aluminium alloy			
[6]	Belt pulley	High-alloy stainless steel			
	Note on materials	RoHS-compliant			
		Contains paint wetting impairment substances			

# Data sheet

Technical data – Displacement encoder			Dimensions → page 26
Туре		ELGAM1	ELGAM2
Resolution	[µm]	2.5	10
Max. travel speed	[m/s]	4	4
with displacement encoder			
Encoder signal		5 V TTL; A/A, B/B; reference signal (N/N) cyclically every 5 mn	n (zero pulse)
Signal output		Line driver, alternating, resistant to sustained short circuit	
Electrical connection		8-pin plug, round design, M12	
Cable length	[mm]	160	

Operating and environmental conditions – Displacement encoder system					
Ambient temperature	[°C]	-10 +70			
Degree of protection		IP64			
CE marking (see declaration of conformity)		To EU EMC Directive <sup>1)</sup>			

1) For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp  $\rightarrow$  Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

#### Application information

The spindle axis with displacement encoder is not designed for the following application examples:





• Welding application



#### **Characteristic load values**

The indicated forces and torques refer to the centre of the guide. The point of application of force is the point where the centre of the guide and the longitudinal centre of the slide intersect. These values must not be exceeded during dynamic operation. Special attention must be paid to the cushioning phase.



Distance from the slide surface to the centre of the guide



I

Distance from the slide surface to the centre o	f the guide
Size	70

Size		70	80	120	150
Dimension x	[mm]	37	50	70	86

#### Max. permissible forces and torques for a service life of 5000 km

Size		70	80	120	150
Fy <sub>max.</sub>	[N]	1500	2500	5500	11000
Fz <sub>max</sub>	[N]	1850	3050	6890	11000
Mx <sub>max.</sub>	[Nm]	16	36	104	167
My <sub>max.</sub>	[Nm]	132	228	680	1150
Mz <sub>max.</sub>	[Nm]	132	228	680	1150

# - 🎍 - Note

For a guide system to have a service life of 5000 km, the load comparison factor must have a value of fv  $\leq$  1, based on the maximum permissible forces and torques for a service life of 5000 km.

If the axis is subjected to two or more of the indicated forces and torques simultaneously, the following equation must be satisfied in addition to the indicated maximum loads:

Calculating the load comparison factor:

$$f_{v} = \frac{\left|F_{y1}\right|}{F_{y2}} + \frac{\left|F_{z1}\right|}{F_{z2}} + \frac{\left|M_{x1}\right|}{M_{x2}} + \frac{\left|M_{y1}\right|}{M_{y2}} + \frac{\left|M_{z1}\right|}{M_{z2}} \le 1$$

 $F_1/M_1$  = dynamic value  $F_2/M_2$  = maximum value

#### Calculating the service life

The service life of the guide depends on the load. To be able to make a statement as to the service life of the guide, the graph below plots the load comparison factor fv against the service life.

#### Load comparison factor $f_v$ as a function of service life

#### Example:

A user wants to move an X kg load. Using the formula ( $\rightarrow$  page 16) gives a value of 1.5 for the load comparison factor f<sub>v</sub>. According to the graph, the guide would have a service life of approx. 1500 km. Reducing the acceleration reduces the Mz and My values. A load comparison factor f<sub>v</sub> of 1 now gives a service life of 5000 km.





#### - 📲 - Note

Engineering software Electric Motion Sizing www.festo.com/x/electric-motionsizing The engineering software can be used to calculate the guide workload for a service life of 5000 km.  $f_{\rm v}$  > 1.5 are only theoretical comparison values for the recirculating ball bearing guide.

#### Comparison of the characteristic load values for 5000 km with dynamic forces and torques of recirculating ball bearing guides

The characteristic load values of bearing guides are standardised to ISO and JIS using dynamic and static forces and torques. These forces and torques are based on an expected service life of the guide system of 100 km to ISO or 50 km to JIS. As the characteristic load values are dependent on the service life, the maximum permissible forces and torques for a 5000 km service life cannot be compared with the dynamic forces and torques of bearing guides to ISO/JIS.

To make it easier to compare the guide capacity of linear axes ELGA with bearing guides, the table below lists the theoretically permissible forces and torques for a calculated service life of 100 km. This corresponds to the dynamic forces and torques to ISO.

These 100 km values have been calculated mathematically and are only to be used for comparing with dynamic forces and torques to ISO. The drives must not be loaded with these characteristic values as this could damage the axes.

#### Max. permissible forces and torques for a theoretical service life of 100 km (from a guide perspective only)

Size	70	80	120	150
Fy <sub>max.</sub> [N]	5520	9200	20240	40480
Fz <sub>max</sub> [N]	6808	11224	25355	40480
Mx <sub>max.</sub> [Nm	n] 59	132	383	615
My <sub>max.</sub> [Nm	i] 486	839	2502	4232
Mz <sub>max.</sub> [Nm	i] 486	839	2502	4232

### Data sheet



ELGA-TB-KF-70

ELGA-TB-KF-80

ELGA-TB-KF-120

1000 1500 2000 2500 3000 3500 4000

n [1/min]

1

0

0

500



#### 2023/08 - Subject to change

L18

### Data sheet

#### 2nd moments of area

Z-axis

axis

Size		70	80	120	150
ly	[mm <sup>4</sup> ]	1.46x10 <sup>5</sup>	2.57x10 <sup>5</sup>	1.26x10 <sup>6</sup>	4.62x10 <sup>6</sup>
lz	[mm <sup>4</sup> ]	4.59x10 <sup>5</sup>	9.14x10 <sup>5</sup>	4.37x10 <sup>6</sup>	12.32x10 <sup>6</sup>

#### Maximum permissible support spacing L (without profile mounting MUE/central support EAHF) as a function of force F

In order to limit deflection in the case of large strokes, the axis may need to be supported.

The following graphs can be used to determine the maximum permissible support spacing l as a function of force F acting on the axis. The deflection is f = 0.5 mm.







L[mm]

Recommended deflection limits

Adherence to the following deflection limits is recommended so as not to impair the functionality of the axes.

Greater deformation can result in increased friction, greater wear and reduced service life.

Size	Dynamic deflection	Static deflection
	(moving load)	(stationary load)
70 150	0.05% of the axis length, max. 0.5 mm	0.1% of the axis length

## Data sheet

#### **Central lubrication**

The lubrication connections enable the guide of the toothed belt axis ELGA-TB-KF to be permanently lubricated in applications in humid or wet ambient conditions using semi- or fully automatic relubrication devices.

#### Design of a central lubrication system

A central lubrication system requires various additional components. The illustration shows different options (using a hand pump, pneumatic container pump or electric container pump) required as a minimum for designing a central lubrication system. Festo does not sell these additional components; however, they can be obtained from the following companies:

- Lincoln
- Bielomatik
- SKF (Vogel)

Festo recommends these companies because they can supply all the necessary components.

- The connection options are already available in the standard design of the axes
- There is a dedicated lubrication connection for the spindle nut and the two ball cassettes

Slide dimensions → page 24

8

spindle nut and tes

1

5

4

- [1] Hand pump
- [2] Pneumatic container pump
- [3] Electric container pump
- [4] Manually operated container pump
- [5] Nipple block
- [6] Distributor block
- [7] Tubing or piping
- [8] Fittings





Size	B10	B11	H10
70	67	40	20
80	80	40	20
120	116	40	20
150	150	80	20

### Data sheet



10

5

5.1

6

- 9

2.1

2.1

7.5

9.7\_0.2

3.1

4.2

5.6

4.6\_0.1

5.9<sub>-0.1</sub>

90

74

70

80

120

40

20

44

20



120	55	20	M6	M5	9	M5	M6	24.5	6	335
150	90	40	M6	M8	9	M5	M6	23	7±0.1	378.4
Size	L2	L3	L4	L5	L6	T1	T2	T3	T4	T6
	±0.1	±0.1	±0.2	±0.03	±0.2			+0.1		
120	140	48	116	40	76	8	9.7	2.1	12.6-0.3	6
150	200	60	169	40	99	7.5	10.7	2.1	11	7

### Dimensions



### Ordering data

Key features:

- Stroke reserve: 0 mm
- Standard slide

Size	Stroke	Part no.	Туре
	[mm]		
70	300	8041851	ELGA-TB-KF-70-300-0H
	400	8041852	ELGA-TB-KF-70-400-0H
	500	8041853	ELGA-TB-KF-70-500-0H
	600	8041854	ELGA-TB-KF-70-600-0H
	800	8041855	ELGA-TB-KF-70-800-0H
	1000	8041856	ELGA-TB-KF-70-1000-0H
	1200	8041857	ELGA-TB-KF-70-1200-0H
80	400	8041858	ELGA-TB-KF-80-400-0H
	500	8041859	ELGA-TB-KF-80-500-0H
	600	8041860	ELGA-TB-KF-80-600-0H
	800	8041861	ELGA-TB-KF-80-800-0H
	1000	8041862	ELGA-TB-KF-80-1000-0H
	1200	8041863	ELGA-TB-KF-80-1200-0H
			r
120	400	8041864	ELGA-TB-KF-120-400-0H
	500	8041865	ELGA-TB-KF-120-500-0H
	600	8041866	ELGA-TB-KF-120-600-0H
	800	8041867	ELGA-TB-KF-120-800-0H
	1000	8041868	ELGA-TB-KF-120-1000-0H
	1200	8041869	ELGA-TB-KF-120-1200-0H
	1500	8041870	ELGA-TB-KF-120-1500-0H

# Ordering data - Modular product system



# Ordering data – Modular product system

Ordering table

Ordering table								
Size		70	80	120	150	Conditions	Code	Enter code
Module no.		8024914	8024915	8024916	8024917			
Design		Linear axis					ELGA	ELGA
Function		Toothed belt					🛧 -TB	-TB
Guide		Recirculating ball	bearing guide				🛧 -KF	-KF
Size	[mm]	70	80	120	150		☆	
Stroke length	[mm]	1 5000	1 8500	1 8500	1 7000		☆	
Stroke reserve	[mm]	0 999 (0 = no s	stroke reserve)			[1]	🗙H	
Additional slide		Without					☆	
		1 slide left					📩 -ZL	
		1 slide right					📩 -ZR	
Protection against particles		Standard						
		Cover strip with n	nagnetic deflectio	1			P11	
Displacement encoder, incremental		Without					☆	
		Resolution 2.5 µr	n				-M1	
		Resolution 10 µm	l				-M2	
Displacement encoder attachment position		Without					☆	
		Rear				[2]	В	
		Front				[2]	F	
Material of toothed belt		Chloroprene rubber						
		Coated PU					-PU2	

[1] ... H The sum of the nominal stroke and 2x stroke reserve must be at least 50 mm and must not exceed the maximum stroke length

[2] **B**, **F** Only with displacement encoder M1, M2

Festo core product range

Generally ready for shipping ex works in 24 hours